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Visual Cloud Accelerator Card - Rendering Software Installation Guide

Visual Cloud Accelerator Card - Rendering Software Installation Guide

December 2019
Order No.: 611522-3.0
User Guide
## Revision History

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<tr>
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| December 2019 | 3.0     | 1.1 **Introduction** on page 7: Updated section for name change of Android solution.  
1.2 **Hardware Configuration** on page 8: Added links to hardware specifications datasheet and Celestica support.  
1.3 **Build Machine Requirement** on page 9: Updated link to docker installation.  
1.6.2.2 **Setup nginx/RTMP Server** on page 12: Added more details about nginx and RTMP module.  
2.1.2 **VCAC-R Contents of the Release Package** on page 22: Updated links to various components for the release.  
2.1.3 **Hardware Configuration** on page 23: Added links to hardware specifications datasheet and Celestica support.  
2.1.4 **Software Configuration** on page 24: Updated version information in table.  
2.2.3 **Build Machine Requirement** on page 25: Updated link to docker installation.  
2.2.5 **Build Host Kernel and VCAC-R Driver** on page 26: Updated links for the current release.  
2.2.6.1 **Windows Tools** on page 27: Updated links to latest components.  
2.2.7.2 **VCAC-R Software Installation on Host** on page 30: Updated commands for filenames.  
2.2.7.3 **Accessing VCAC-R Card via Host Using DHCP Setup** on page 31: Updated Commands.  
2.2.7.4 **VCAC-R Card Boot up with vcad Image** on page 32: Updated commands.  
2.2.7.5 **PXE Feature Description** on page 33: Added new chapter.  
2.1.2.2 **Setup nginx/RTMP Server** on page 12: Added more details about nginx and RTMP module.  
2.1.3 **Hardward Configuration** on page 23: Added links to hardware specifications datasheet and Celestica support.  
2.1.4 **Software Configuration** on page 24: Updated version information in table.  
2.2.3 **Build Machine Requirement** on page 25: Added additional links.  
2.2.5 **Build Host Kernel and VCAC-R Driver** on page 26: Updated links for the current release.  
2.2.6.1 **Windows Tools** on page 27: Updated links to latest components.  
2.2.7.2 **VCAC-R Software Installation on Host** on page 30: Updated commands for filenames.  
2.2.7.3 **Accessing VCAC-R Card via Host Using DHCP Setup** on page 31: Updated Commands.  
2.2.7.4 **VCAC-R Card Boot up with vcad Image** on page 32: Updated commands.  
2.2.7.5 **PXE Feature Description** on page 33: Added new chapter.  
2.2.8 **PXE Feature Description** on page 33: Added a new chapter.  
2.3 **Additional Specific Software Requirements** on page 34: Updated section.  
2.5 **Automatic Environment Configuration** on page 36: Added a new chapter.  
2.7 **End to End E2E Measurement** on page 49: Added a new section on end to end latency measurement.  
2.10 **E2E Latency Measurement** on page 49: Added a new section on end to end latency measurement. |
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1.2 **Hardware Configuration** on page 8: Updated CPU information.  
1.3 **Build Machine Requirement** on page 9: Added new chapter.  
1.4 **Setup Proxy for Docker (if needed)** on page 9: Added new chapter.  
1.5.1 **README.txt** on page 9: Added new section.  
1.5.9 **build.sh** on page 10: Updated kernel version information.  
1.6.1 **Preparation** on page 10: Updated directory structure.  
1.6.2.1 **Update Host Kernel** on page 12: Updated version of linux kernel.  
1.6.2.4 **Install VCA Software** on page 14: Added instructions for updating BIOS And EEPROM.  
1.6.2.5 **Start ICR Service in VCA Node** on page 16: Updated commands and text for clarity.  
1.7.1.1 **Initiate Streaming Service in VCA Node** on page 17: Updated commands.  
2.1.1 **Architecture** on page 21: Updated architecture diagram to reflect support for DX9.  
2.1.3 **Hardware Configuration** on page 23: Updated CPU information.  
2.2.6.1 **Windows Tools** on page 27: Added more details about installation components.  
2.2.7.3 **Accessing VCAC-R Card via Host Using DHCP Setup** on page 31: Added new topic.  
2.3 **Additional Specific Software Requirements** on page 34: Added information about Vulkan SDK and chrome browser.  
2.5 **Automatic Environment Configuration** on page 36: Reorganized the chapter for clarity.  
2.10 **E2E Latency Measurement** on page 49: Added a new section on end to end latency measurement. |
## Revision History

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<tr>
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<td>Removed the reference to the appendix on page 50.</td>
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</tr>
</tbody>
</table>

Appendix A Intel® VCA Utility (vcactl) on page 50: Added a chapter on Intel VCA Utility (vcactl).
1.0 Android Solution

1.1 Introduction

The purpose of this section of the document is to provide guidance on how to use the release package for Cloud Gaming Reference Solution for Android on platforms with Intel CPU and integrated GPU. Hereafter, Visual Compute Accelerator card will be referred to as VCA. The software guide can be used for VCAC-R (Visual Cloud Accelerator Card - Rendering), so the terms will be used interchangeably.

Solution contains the following main parts:


2. Intel Cloud Rendering (ICR): The ICR front-end receives rendering requests from the Android game app and Android framework, converts those requests to command streams and sends them to the ICR back-end. The ICR back-end performs real rendering and encoding on the accelerator card GPU, and then sends the video stream.
3. Visual Cloud Accelerator Card - Rendering: Provides high-density GPU rendering capability and high-performance hardware video codec, with whole software stack including user mode middleware, user mode drivers, and kernel mode drivers.

4. Scripts to build and setup the entire reference solution.

1.2 Hardware Configuration

The following table describes recommended hardware configuration:

A Server with 2nd Generation Intel® Xeon® processor is recommended as the host to mount the VCAC-R card through PCIe.

Table 1. Recommended System Hardware Configuration

<table>
<thead>
<tr>
<th>Component Type</th>
<th>Part Name</th>
</tr>
</thead>
<tbody>
<tr>
<td>KNOCK DOWN KIT</td>
<td>Intel® Server System R2312WFTZS 12x3.5in 2x10GbE</td>
</tr>
<tr>
<td>CPU</td>
<td>Intel® Xeon™ Platinum 8280M Processor 38.5M Cache, 2.70 GHz *2</td>
</tr>
<tr>
<td>MEMORY</td>
<td>16GB 2666 Reg ECC 1.2V DDR4 Crucial CT16G4RFD8266 or Micron® MTA18ASF2G72PDZ-2G6D1 *12</td>
</tr>
<tr>
<td>ATA HARD DRIVE</td>
<td>960GB SSD 2.5in SATA 3.0 6Gb/s Intel® Youngsville SE SSDSC2KB960G701 DC S4500 Series</td>
</tr>
<tr>
<td>Add-in Card</td>
<td>Intel® Visual Cloud Accelerator card - Rendering (VCAC-R)*2</td>
</tr>
<tr>
<td>NETWORK ADAPTER</td>
<td>On Board</td>
</tr>
<tr>
<td>CHASSIS COMPONENT</td>
<td>PCIe 2U Riser Spare Intel® A2UL16RISER2 (2 Slot)</td>
</tr>
<tr>
<td>CHASSIS COMPONENT</td>
<td>Passive Airduct Bracket Kit Intel® AWFCOPRODUCTBKT</td>
</tr>
<tr>
<td>CHASSIS COMPONENT</td>
<td>Passive Airduct Kit Intel® AWFCOPRODUCTAD</td>
</tr>
<tr>
<td>HEATSINK</td>
<td>Included</td>
</tr>
</tbody>
</table>

Table 2. VCAC-R Hardware Configuration

<table>
<thead>
<tr>
<th>Board Feature Set</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CPU</td>
<td>2* Intel® Core(TM) i7-8709G CPU @ 3.10GHz</td>
</tr>
<tr>
<td>Intel GPU</td>
<td>Mesa DRI Intel® HD Graphics 630</td>
</tr>
<tr>
<td>AMD GPU</td>
<td>Radeon™ RX Vega M GH Graphics</td>
</tr>
<tr>
<td>Memory</td>
<td>8G*2 per CPU; DDR4 2400 ECC SODIMMs, 2 channels per CPU</td>
</tr>
<tr>
<td>PCIe* configuration</td>
<td>Gen3, x16, 8 lanes per CPU</td>
</tr>
<tr>
<td>BIOS</td>
<td>1* 16 MB SPI flash per CPU</td>
</tr>
<tr>
<td>HEATSINK</td>
<td>Included</td>
</tr>
</tbody>
</table>


NOTE
Customers need to work with their Celestica sales representative to get credentials for the website.

1.3 Build Machine Requirement
The build machine for acgss should meet the following requirements:

- Linux based OS: the scripts are tested on Ubuntu 16.04
- Docker installed: Docker is used in the build process. Refer to https://docs.docker.com/install/linux/docker-ce/ubuntu/ for how to install Docker (Community Edition).
- User privilege: root account (or sudo) is required to give set up permissions for user to use docker.

1.4 Setup Proxy for Docker (if needed)
Internet connection is needed to build Docker container, download source code and dependencies. If you are behind proxy, it needs to be setup for Docker.

1.5 Build acgss Package from Source Code
End users can employ several scripts to download open source code for project components from the Internet. More details are given in the sections below.

1.5.1 README.txt
There is a README.txt which guides user on how to build acgss package from the source code and lists all the commands that user needs to run.

1.5.2 source/rr_code
There is icr (Intel Cloud Rendering) front-end source code provided in source/rr_code, which will be built into AIC.

1.5.3 docker/Dockerfile
There is a Dockerfile to provide build environment which contains all environment dependencies. As a first step, a user needs to build and run docker image built by this Dockerfile.

1.5.4 patches/dependencies
There are necessary dependencies/code patches that exist in patches/dependencies.

1.5.5 patches/aosp
There are necessary bsp(board support package) projects which include aosp(Android Open Source Project) patches that exist in patches/aosp directory.
1.5.6 patches/package

There are deployment scripts and documents which get packaged into acgss package.

1.5.7 recipe.json

There is a recipe.json file which describes all required open source project components. For each project component, it describes its url, branch, revision. For example:

```json
"libva": {
  "url": "https://github.com/intel/libva",
  "branch": "master",
  "revision": "250b3dc8f370bc6d85be767c9722fd98e8b02ebb"
},
```

1.5.8 download.py

Using the information from recipe.json on page 10, a download script named download.py, can download all required source code from Internet. In addition, there are some local patches, which will be applied to the open source project components by the build script as in build.sh on page 10.

1.5.9 build.sh

A build script named build.sh builds system in the following sequence:

1. 4.14 kernel
2. 4.19.0 kernel
3. 4.14 modules and 4.19.0 modules
4. Host daemon
5. Handle vcad image build dependencies and create vcad image
6. Build out ICR(Intel Cloud Rendering) back-end
7. Build out AIC image
8. Package

Final compressed file acgss-$version.tar.gz will be generated once all steps are done.

1.6 Install Software with Binary

1.6.1 Preparation

Prepare host system (2nd Generation Intel® Xeon® Scalable Processor) with VCAC-R card installed ready, with Ubuntu16.04 LTS OS installed on host.

The host system BIOS must be configured to enable large Memory-Mapped Input/Output (MMIO), and allow for large per-device BAR (Base Address Register) allocations. BAR must have 64-bit address enabled.

The minimum requirements for BAR and MMIO are:
MMIO mapping above 4 GB is enabled  
Minimum MMIO size is 4 GB/CPU (node)

For example, on Intel® Server Board S2600WT based systems, this can be enabled in BIOS setup by configuring the following two options on the PCI Configuration screen:

- Set Memory Mapped Above 4 GB to Enabled
- Set Memory Mapped IO size to 256 GB or higher

Get Android cloud gaming software stack package (acgss) from steps in Build acgss Package from Source Code on page 9. It is a compressed file named as acgss-$version.tar.gz. The software stack has support for both baremetal and VM pass through solutions.

Download the file and extract to current path. Then you can find a directory in ./acgss. Expanded directory structure is shown below:

```
acgss
  ├── host
  │   └── 1-deploy_vca.sh
  │
  │   └── aic-rr
  │       ├── aic
  │       │   └── aic-manager.tar.gz
  │       └── android.tar.gz
  │
  │   └── kernel
  │       ├── linux-headers-4.14.xxxxxxx-xxx.vca+2019xxxx_amd64.deb
  │       └── linux-images-4.14.xxxxxxx-xxx.vca+2019xxxx_amd64.deb
  │
  │   └── vca
  │       └── daemon-vca-xx-amd64.deb
  │
  │   └── vca_disk24_reference_k4.19.0-1Ubuntu16.04-xx.xx.vcad.gz
  │
  │   └── vcass-modules-xxxxxx_amd64.deb
  │
  │   └── 00-net.rules
  │
  │   └── icr
  │
  │       └── release_irr_build
  │
  │       └── intel-cloud-rendering_ubuntu-16.04_xxxxxxxxx .tgz
  │
  │   └── irr_test_tool
  │
  │       └── script
  │
  │       └── rr_server_file
```
1.6.2 Setup SW in Host

Steps for setting up software in the host system are listed in the sections below.

1.6.2.1 Update Host Kernel

1. Install updated kernel package

```
$ cd acgss/host/kernel
$ sudo dpkg -i ./linux-headers-<kernel_ver>.<version>.amd64.deb
$ sudo dpkg -i ./linux-images-<kernel_ver>.<version>.amd64.deb
```

2. Configure the new kernel as default boot option

   Edit `/etc/default/grub`,

   Change the setting

   ```
   GRUB_DEFAULT=0
   ```

   to

   ```
   GRUB_DEFAULT="Advanced options for Ubuntu>Ubuntu, with Linux4.14-xxx-xx.vca+
   ```

   **NOTE**

   Kernel name of "Ubuntu, with Linux 4.14-xxx-xx.vca+" is obtained from the menuentry output of

   ```
   $ cat /boot/grub/grub.cfg | grep menuentry
   ```

3. Reload grub

   ```
   $ sudo update-grub
   ```

4. Reboot system

   ```
   $ sudo reboot
   ```

1.6.2.2 Setup nginx/RTMP Server

Download the nginx source code, assume it will be downloaded to `acgss/host/nginx`:

```
$ wget http://nginx.org/download/nginx-1.13.1.tar.gz
```

**NOTE**

You can find the latest version on the nginx download page.

Get the RTMP module source code from git:

```
$ wget https://github.com/arut/nginx-rtmp-module/archive/master.zip
```
Navigate to nginx directory

```
sudo apt-get install openssl libssl-dev libpcre3 libpcre3-dev
$ cd acgs/host/nginx
```

1. Extract both zip files present in the folder and go to nginx-1.13.1 directory

```
$ tar -zxvf nginx-1.13.1.tar.gz
$ unzip master.zip
$ cd nginx-1.13.1
```

2. Build nginx

```
$ ./configure --with-http_ssl_module --add-module=../nginx-rtmp-module-master
$ make
$ sudo make install
```

nginx is installed, default installation path is /usr/local/nginx.

3. Configure nginx to use RTMP

Open config file which is located by default at /usr/local/nginx/conf/nginx.conf and add the following lines at the very end of the file:

```
rtmp {
    server{
        listen 1935;
        chunk_size 4096;
        application demo{
            live on;
            record off;
        }
    }
}
```

4. Start nginx server

```
$ sudo /usr/local/nginx/sbin/nginx
```

To verify nginx is running, navigate to the browser and enter http://localhost:8080, you should get the "Welcome to nginx!" page.

5. Configure nginx to auto-start at system reboot

Add /usr/local/nginx/sbin/nginx to /etc/rc.local, see file example:

```
#!/bin/sh -e
#
# rc.local
#
# This script is executed at the end of each multiuser runlevel.
# Make sure that the script will "exit 0" on success or any other
# value on error.
#
# In order to enable or disable this script, just change the execution
# bits.
#
# By default this script does nothing.
```

1.6.2.3 **Setup Docker**

Refer to [https://docs.docker.com/install/linux/docker-ce/ubuntu/](https://docs.docker.com/install/linux/docker-ce/ubuntu/) for detailed steps to install docker.

Optional reference to setup docker: [https://docs.docker.com/config/daemon/systemd/](https://docs.docker.com/config/daemon/systemd/)

1.6.2.4 **Install VCA Software**

There is one key deployment script developed to combine the VCA software installation and deployment process. It includes VCA daemon tool installation, loading vcad and configuring auto boot of vca nodes every time the host system restarts.

There are 2 systemd services (loadvcad.service and bootvca.service) provided for managing VCA image load and vca boot status.

```
$ cd acgss/host
$ ./1-deploy_vca.sh
```

**NOTE**

It takes about 10-15 minutes for VCA image setup at first time. User may need to reboot if there is a message saying "VCA software install done, please reboot and wait about 10-15 minutes to load vcad."

Login to VCA node with the username and password set during build (take node00 as example):

```
$ ssh root@172.33.1.1
password: vista1
```
NOTE
The EEPROM and BIOS of VCAC-R are also available in the public website. User can find them from the following links:

EEPROM: https://01.org/openvisualcloud/download
BIOS: https://hardwaresupport.celestica.com

Following steps can be referred to flash the EEPROM and BIOS in need, but user is not recommended to upgrade EEPROM and BIOS by themselves unless there are critical bug fixes.

Update BIOS:
1. Power on the host.
2. Unzip the downloaded VCAC-R BIOS update package.
3. Reset the node using the following command:
   $ sudo vcactl reset
4. Wait for the reset to complete; the command sudo vcactl wait-BIOS or sudo vcactl status returns bios_up when ready.
5. Run the following command:
   $ sudo vcactl update-BIOS <BIOS file name>
6. Wait for the update to complete; the command sudo vcactl wait-BIOS or sudo vcactl status returns bios_up when ready.
7. After BIOS update is complete, the node(s) reboot to come online with the new BIOS version.
8. When the last command finishes successfully, G3 (mechanical off) is necessary. To perform G3, execute the power off command on the host and then disconnect from the power supply for 15 seconds.

Update EEPROM:
1. Unzip the downloaded VCAC-R EEPROM Update package
2. Reset the node using the following command:
   $ sudo vcactl reset
3. Wait for the reset to complete; the command sudo vcactl wait-BIOS or sudo vcactl status returns bios_up when ready.
4. Run the following command:
   $ sudo vcactl update-EEPROM <EEPROM file name>
5. When the last command finishes successfully, reboot the host. After rebooting, the software installation is complete.
1.6.2.5  

Start ICR Service in VCA Node

1. Copy icr software to vca node

   ```
   root@vca_node_00:~# scp -r <username>@172.33.1.254:~/acgss/icr/ ~
   ```

2. Stop and disable firewall

   ```
   root@vca_node_00:~# systemctl stop firewalld.service
   root@vca_node_00:~# systemctl disable firewalld.service
   root@vca_node_00:~# systemctl status firewalld.service
   ```

3. Install icr

   Extract acgss/icr/release_irr_build/intel-cloud-rendering_<irr-version>.tgz and install icr

   ```
   root@vca_node_00:~# tar zxvf ~/icr/release_irr_build/intel-cloud-rendering_<irr-version>.tgz -C ~
   root@vca_node_00:~# cd ~/intel-cloud-rendering_<irr-version>/
   root@vca_node_00:~# ./install.sh
   ```

4. Install AMD driver in vca node

   a. Configure proxy and dns to use apt install software.


      Click Ubuntu x86 64-Bit and then scroll to Radeon Software for Linux Driver for Ubuntu 18.04.1 and click Download button.

      ```
      root@vca_node_00:~# tar xvf amdgpu-pro-18.40-697810-ubuntu-18.04.tar
      root@vca_node_00:~#  cd amdgpu-pro-18.40-697810-ubuntu-18.04
      root@vca_node_00:~#  sed -i '/LIB32_META_PACKAGE=amdgpu-lib32/d' amdgpu-install
      root@vca_node_00:~#  sed -i '/LIB32_OPENGL_META_PACKAGE=amdgpu-pro-lib32/d' amdgpu-install
      root@vca_node_00:~#  ./amdgpu-install
      ```

      If user meets amdgpu-lib32 dependencies error, please run following command:

      ```
      root@vca_node_00:~# dpkg --add-architecture i386
      ```

   c. Setup and start xorg service

      ```
      root@vca_node_00:~# cp ~/irr_test_tool/xorg.conf /etc/X11
      root@vca_node_00:~# cp ~/irr_test_tool/xorg.service /lib/systemd/system/
      root@vca_node_00:~# systemctl start xorg.service
      root@vca_node_00:~# systemctl enable xorg.service
      ```

   d. Check the OpenGL renderer string is AMD VEGAM

      ```
      root@vca_node_00:~# glxinfo |grep render
      OpenGL vendor string: X.Org
      OpenGL renderer string: AMD VEGAM (DRM 3.27.0 AMD 18.30 ,
      ```
5. **Check streaming connection with following command**

```
root@vca_node_00:~# cd ~/irr_test_tool/
root@vca_node_00:~# ./irr start -n 1 -url rtmp -brc cqp
```

This command will help user to setup 1x ICR instance with rtmp path, and brc mode is CQP. See ./irr start -h for detailed usage. See ./irr show -h to see help to check ICR instance status.

There should be no error message reported in journalctl log, connection will be established once AIC is started. Make sure nginx server has started on host before initiating ICR instance with rtmp path.

### 1.7 Usage Scenarios

#### 1.7.1 Multi-thread Remote Render

##### 1.7.1.1 Initiate Streaming Service in VCA Node

1. Check firewall status

```
root@vca_node_00:~# systemctl status firewalld.service
```

Refer to **Start ICR Service in VCA Node** on page 16 to disable firewall if the status is active.

2. **Initiate 20** threads of remote rendering service from 172.33.1.1. The rtmp streaming server is located on host. The default host ip is 172.33.1.254 for VCA node00.

```
root@vca_node_00:~# cd ~./irr_test_tool
root@vca_node_00:~# ./irr start -n 20 -url rtmp -brc cqp
```

There should be no error message reported with "systemctl status irr.$[i]" after streaming setup. $[i] should be 1,2,3..20.

##### 1.7.1.2 Set Up AIC and Install Game

1. Open another terminal and login to host.

2. Prepare remote render service config file for AIC to install multi-threads of android instance.

Refer to `acgss/script/rr_server_file` for remote render service configuration file example. Note that the IP and the port must match with the setting to initiate remote render service in **Initiate Streaming Service in VCA Node** on page 17.
3. Install 20 android instances, specify adb port, RR server. For example:

```
$ cd acgss/host/aic-rr
$ ./aic install -n 20 -e -b 5590 -l server -f acgss/script/rr_server_file
```

4. Start AIC

```
$ ./aic start
```

It will report “found a guest connection” and FPS will display on VCA side once android connects to remote render service.

5. Install game

Refer to acgss/script/install_apk.sh to install target game apk. For example:

```
$ ./install_apk.sh 20 ~/dtpkbd_1499043809924.apk
```

6. Display the streaming

Streaming could be received on any devices within the LAN. Find a laptop or PC and connect to the LAN, install video player (take vlc as example), run the cmd “vlc.exe rtmp://<The host IP>/demo/i.flv” (i is a number from 1 to 20) to display the streaming.

### 1.7.2 Null-Render Usage

Use either adb or docker Command to Enable Null Rendering Function.

```
$ sudo docker exec -tid android0 sh -c "setprop debug.egl.skipDraw 1"
$ sudo docker exec -tid android0 sh -c "setprop debug.egl.skipSwap 1"
```

OR

```
$ adb shell
> setprop debug.egl.skipDraw 1
> setprop debug.egl.skipSwap 1
```

The display output will stop responding to mouse movement indicating null rendering works. Set both properties to 0 to disable null rendering. Display refresh will be restored.

### 1.8 Reference Steps to Setup VCA Manually

#### 1.8.1 Install VCA Software

```
$ cd acgss/host/vca
$ sudo apt install ./daemon-vca_<vca_version>-amd64.deb
```

#### 1.8.2 Load VCA Image and Configure VCA

Navigate to the vca directory:
1. Load VCA image

Extract the persistent image copy for each node. Make sure that each node has its own copy.

**NOTE**
The extracted .vcad file needs 10GB of free disk space.

```
$ cd acgss/host/vca/
$ mkdir -p acgss/host/vca/node00
$ tar -xvf vca_reference_<vca-image-version>.tar.bz2 -C acgss/host/vca/node00
```

Add the extracted vca_disk image as the primary BlockIO device.

```
$ sudo vcactl blockio open 0 0 vcablk0 RW acgss/host/vca/node00/
    vca_reference_<vca-image-version>.vcad
```

**NOTE**
If you want to boot more than 1 vca node (e.g. to boot 2 nodes), the following steps are needed:

```
$ mkdir acgss/host/vca/node01
$ cp acgss/host/vca/node00/vca_reference_<vca-image-version>.vcad acgss/host/vca/node01
$ sudo vcactl blockio open 0 0 vcablk0 RW acgss/host/vca/node01/
    vca_reference_<vca-image-version>.vcad
```

2. Configure IP of VCA node

Refer to the script acgss/script/enable_nat.sh to enable NAT config.

1.8.3 Boot VCA Nodes

1.8.3.1 Check VCA Status

Make sure all pre-boot nodes are in the correct status.

```
$ sudo vcactl status
```

It should return the following status:

| Card: 0 Cpu: 0 STATE: bios_up |
| Card: 0 Cpu: 1 STATE: bios_up |

If not, run the following command and wait for all nodes to be ready

```
$ sudo vcactl wait-BIOS
```
1.8.3.2 Boot VCA Node and Login

Add udev rules for the VCA virtual interfaces (eth0/eth1/eth2) to avoid to be managed by NetworkManager. This is critical since the service may block communication between the host and Intel® VCA card.

Add the following lines to /etc/udev/rules.d/00-net.rules

```
ACTION=="add", SUBSYSTEM=="net",KERNEL=="eth0", ENV{NM_UNMANAGED}"="1"
ACTION=="add", SUBSYSTEM=="net",KERNEL=="eth1", ENV{NM_UNMANAGED}"="1"
```

Use /etc/init.d/udev restart command to let it take effect if you don't want to reboot the server.

Boot VCA node:

```
$ sudo vcactl boot 0 0 vcablk0
```

Check the status for return value net_device_ready:

```
$ sudo vcactl status
Card: 0 Cpu: 0 STATE: net_device_ready
Card: 0 Cpu: 1 STATE: bios_up
```
2.0 Windows Based Solution

2.1 Introduction

The purpose of this chapter is to provide guidance on how to use Cloud Gaming for Windows reference solution on Windows 10 OS. It describes how to configure environment for building this solution and how to run it.

This product is based on open source GamingAnywhere (GA) solution, which is available on public github (http://gaminganywhere.org/). It provides end to end solution for cloud gaming, based on client–server architecture. Base solution has been modified and improved to benefit from the advantages provided by Intel hardware architecture. Modified code is provided as a reference solution for future implementations.

2.1.1 Architecture

Architecture of the Cloud Gaming For Windows is based on client-server model of communication. Server is responsible for receiving request from client, launching and getting content from game, encoding the content and sending it to the client. Client is responsible for connecting to the server, receiving the content from server, decoding content and displaying it on the client screen.

The following figure describes the architecture:
2.1.2 VCAC-R Contents of the Release Package

The contents of release package for VCAC-R based host SW package(kernel modules and user space app) are listed in the table below. Intel® drives these ingredients through continuous development and validation to ensure that software updates will perform correctly when integrated into a deployed system.

NOTE
The version of the release software might change. Please refer to the Release Notes Doc. No. 611946 accompanied with the latest Software Releases.

The latest release for VCAC-R Host SW can be found at https://github.com/OpenVisualCloud/VCAC-SW/tree/VCAC-R_R3. User can download it or clone the package from the github link.

Table 3. VCAC-R Contents of Release Package

<table>
<thead>
<tr>
<th>Ingredient</th>
<th>Folders and Contents</th>
</tr>
</thead>
<tbody>
<tr>
<td>VCAC-R host SW package</td>
<td>apps</td>
</tr>
<tr>
<td></td>
<td>buildscripts</td>
</tr>
<tr>
<td></td>
<td>eeprom</td>
</tr>
<tr>
<td></td>
<td>modules</td>
</tr>
<tr>
<td></td>
<td>patches</td>
</tr>
<tr>
<td></td>
<td>windows</td>
</tr>
</tbody>
</table>

continued...
### Ingredient

<table>
<thead>
<tr>
<th>Folders and Contents</th>
</tr>
</thead>
<tbody>
<tr>
<td>README.md</td>
</tr>
<tr>
<td>buildscripts/download_dependencies.sh</td>
</tr>
<tr>
<td>buildscripts/master_build.sh</td>
</tr>
<tr>
<td>buildscripts/windows/windows_part (essential for windows image generation)</td>
</tr>
<tr>
<td>eeprom/VCAC-R/eeprom/VCAC-R (contains DMA-disabled eeprom and normal eeprom)</td>
</tr>
<tr>
<td>windows/vcagent (VCA Agent)</td>
</tr>
</tbody>
</table>

**NOTE**

The EEPROM and BIOS for VCAC-R are also available in the public website. User can find them from the following links:

**EEPROM:** [https://01.org/openvisualcloud/download](https://01.org/openvisualcloud/download)

**BIOS:** [https://hardwaresupport.celestica.com](https://hardwaresupport.celestica.com)

The VCAC-R host SW package contains the following:

- **script ./buildscripts/master_build.sh** to build the VCAC-R host support package including the kernel patch, VCAC-R PCIe driver and VCAC-R utility to be installed on Host server with VCAC-R card.

- **script ./buildscripts/download_dependencies.sh** to download all source dependencies required for build process.

The VCAC-R Card SW package comprises of Cloud Gaming For Windows Application (CloudGamingForWindows.exe). User can follow the links given below to download the application:


### 2.1.3 Hardware Configuration

The following table describes recommended hardware configuration:

A Server with 2nd Generation Intel® Xeon® processor is recommended as the host to mount the VCAC-R card through PCIe.

**Table 4. Recommended System Hardware Configuration**

<table>
<thead>
<tr>
<th>Component Type</th>
<th>Part Name</th>
</tr>
</thead>
<tbody>
<tr>
<td>KNOCK DOWN KIT</td>
<td>Intel® Server System R2312WFTZS 12x3.5in 2x10GbE</td>
</tr>
<tr>
<td>CPU</td>
<td>Intel® Xeon™ Platinum 8280M Processor 38.5M Cache, 2.70 GHz *2</td>
</tr>
</tbody>
</table>

*continued...*
<table>
<thead>
<tr>
<th>Component Type</th>
<th>Part Name</th>
</tr>
</thead>
<tbody>
<tr>
<td>MEMORY</td>
<td>16GB 2666 Reg ECC 1.2V DDR4 Crucial CT16G4RFDB266 or Micron® MT1A8ASF2G72PDZ-2G6D1 *12</td>
</tr>
<tr>
<td>ATA HARD DRIVE</td>
<td>960GB SSD 2.5in SATA 3.0 6Gb/s Intel® Youngsville SE SSDSC2KB960G701 DC S4500 Series</td>
</tr>
<tr>
<td>Add-in Card</td>
<td>Intel® Visual Cloud Accelerator card - Rendering (VCAC-R)*2</td>
</tr>
<tr>
<td>NETWORK ADAPTER</td>
<td>On Board</td>
</tr>
<tr>
<td>CHASSIS COMPONENT</td>
<td>PCIe 2U Riser Spare Intel® A2UL16RISER2 (2 Slot)</td>
</tr>
<tr>
<td>CHASSIS COMPONENT</td>
<td>Passive Airduct Bracket Kit Intel® AWFCOPRODUCTBKT</td>
</tr>
<tr>
<td>CHASSIS COMPONENT</td>
<td>Passive Airduct Kit Intel® AWFCOPRODUCTAD</td>
</tr>
<tr>
<td>HEATSINK</td>
<td>Included</td>
</tr>
</tbody>
</table>

Table 5. VCAC-R Hardware Configuration

<table>
<thead>
<tr>
<th>Board Feature Set</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CPU</td>
<td>2*Intel® Core(TM) i7-8709G CPU @ 3.10GHz</td>
</tr>
<tr>
<td>Intel GPU</td>
<td>Mesa DRI Intel® HD Graphics 630</td>
</tr>
<tr>
<td>AMD GPU</td>
<td>Radeon™ RX Vega M GH Graphics</td>
</tr>
<tr>
<td>Memory</td>
<td>8G*2 per CPU; DDR4 2400 ECC SODIMMs, 2 channels per CPU</td>
</tr>
<tr>
<td>PCIe* configuration</td>
<td>Gen3, x16, 8 lanes per CPU</td>
</tr>
<tr>
<td>BIOS</td>
<td>1* 16 MB SPI flash per CPU</td>
</tr>
<tr>
<td>HEATSINK</td>
<td>Included</td>
</tr>
</tbody>
</table>


NOTE
Customers need to work with their Celestica sales representative to get credentials for the website.

2.1.4 Software Configuration

Software configuration requirements for the hardware listed above are in the table below. Software specific for Cloud Gaming For Windows is described in the next section as Additional Specific Software Requirements on page 34
### Table 6. Recommended Software Configuration

<table>
<thead>
<tr>
<th>Component Type</th>
<th>Part Name</th>
</tr>
</thead>
<tbody>
<tr>
<td>Host OS</td>
<td>CentOS 7.6 3.10.0-957</td>
</tr>
<tr>
<td>Card software on host</td>
<td>VCA SW 2.7</td>
</tr>
<tr>
<td>Card node OS</td>
<td>Windows 10 1803</td>
</tr>
<tr>
<td>Card software</td>
<td>VCA SW 2.7</td>
</tr>
</tbody>
</table>

#### 2.2 Installation

##### 2.2.1 Preparation

The host system BIOS must be configured to enable large Memory-Mapped Input/Output (MMIO), and allow for large per-device BAR (Base Address Register) allocations. BAR must have 64-bit address enabled.

The minimum requirements for BAR and MMIO are:

- MMIO mapping above 4 GB is enabled
- Minimum MMIO size is 4 GB/CPU (node)

For example, on Intel® Server Board S2600WT based systems, this can be enabled in BIOS setup by configuring the following two options on the PCI Configuration screen:

- Set Memory Mapped Above 4 GB to Enabled
- Set Memory Mapped IO size to 256 GB or higher

##### 2.2.2 Build Host Kernel, VCAC-R Driver on Host and VCAC-R System Image

Build host kernel, VCAC-R driver on host and VCAC-R node OS system image using scripts included in the release package. The steps are described in subsequent sections.

##### 2.2.3 Build Machine Requirement

The build machine should meet the following requirements:

- Linux based OS: the scripts are tested on Ubuntu 18.04
- Docker installed: Docker is used in the build process. Refer to [https://docs.docker.com/install/](https://docs.docker.com/install/) for how to install Docker. Minimal required version is Docker 17.05. Further information can be found at [https://docs.docker.com/config/daemon/systemd/](https://docs.docker.com/config/daemon/systemd/) and [https://docs.docker.com/install/linux/postinstall/](https://docs.docker.com/install/linux/postinstall/).
- User privilege: root account (or sudo) is required to give set up permissions for user to use docker.

##### 2.2.4 Setup Proxy for Docker (if needed)

Internet connection is needed to build Docker container, download source code and dependencies. If you are behind proxy, it needs to be setup for Docker.
.buildscripts/master_build.sh would take into account http_proxy environment variable and will pass it to docker. Additional information for setting http proxy can be found at https://docs.docker.com/config/daemon/systemd/.

2.2.5 Build Host Kernel and VCAC-R Driver

VCAC-R latest release can be cloned/downloaded from the link https://github.com/OpenVisualCloud/VCAC-SW/tree/VCAC-R_R3. The contents are mentioned in VCAC-R Contents of the Release Package on page 22 as VCAC-R host SW package. The scripts therein will be used to generate binaries.

README.md will be handy for regular Unix users. master_build.sh and download_dependencies.sh are in "buildscripts" directory.

**NOTE**
All scripts mentioned in this section print usage information when invoked without arguments.

**NOTE**
Single dot (.) in beginning of paths (i.e.: ./buildscripts/master_build.sh) refers to top-level directory of VCAC-R host SW package.

Download all required source dependencies:

```
$ ./buildscripts/download_dependencies.sh --downloads-dir DIRECTORY_TO_STORE_DOWNLOADS
```

Usual http_proxy environment variables will be used by wget utility.

Build host kernel and VCAC-R driver modules and user space utility with the scripts included in the release package. (Run as a user with privileges to use docker). (Switches begin with two minus signs, command should be with three mandatory switches):

```
$./buildscripts/master_build.sh --vca-src-dir PATH_TO_EXTRACTED_VCA_SW_SOURCE_RELEASE_PACKAGE \ 
  --downloads-dir DIRECTORY_WITH_DOWNLOADS_FROM_PREV_STEP \ 
  --out-dir PLACE_TO_PUT_RESULTING_VCA_SW_BINARIES
```

After compilation is completed, the output will be available in requested location above (PLACE_TO_PUT_RESULTING_VCA_SW_BINARIES). Most important parts of its content are following (they will be placed inside separate directories for CentOS and Ubuntu):

- Host kernel packages:
  - kernel-3.10.0-957.el7.centos.2.7.363.VCA.x86_64.rpm
  - linux-image-4.19.0-1.2.7.363.vca_1.0_amd64.deb
- VCAC-R driver module:
  - vcass-modules-3.10.0-957.el7.centos.2.7.363.VCA.x86_64-2.7.363-0.x86_64.rpm
• Utility Application:
  — daemon-vca-2.7.363-x86_64.rpm
  — daemon-vca-2.7.363-x86_64.deb
• These files are also generated:
  — kernel-3.10.0-957.el7.centos.2.7.363.VCA.src.rpm
  — kernel-devel-3.10.0-957.el7.centos.2.7.363.VCA.x86_64.rpm
  — linux-headers-4.19.0-1.2.7.363.vca_1.0_amd64.deb

2.2.6 Build Windows System Image for VCAC-R node

2.2.6.1 Windows Tools

The following hardware and software resources are required to create Windows images:

• Windows drivers and VCAgent service can be downloaded from this link: https://downloadcenter.intel.com/download/28451/Intel-Visual-Compute-Accelerator-VCA1283LVV-VCA1585LMV-Windows-Image-Creation-Package and https://openvisualcloud.github.io/VCAC-SW/windows/vcagent/(latest version of VCAgent service is available here).

• Windows installation ISO (for example, en_windows_10_business_edition_version_1803_updated_jul_2018_x64_dvd_12612769.iso).

• Windows Server 2012/2016 system to perform build operation. System should be at least as up-to-date as the installation ISOs used to create the images and all Microsoft* updates that are available should be installed.

• Oracle VM VirtualBox software (available at https://www.virtualbox.org/wiki/Downloads). These need to be installed prior to the build process.

• Hyper V Server Role installed. This could be selected during Windows Server setup or later using standard techniques via Server Manager -> Manage -> Add Roles and Features Wizard.


• 45 GB of free space. (This is the default amount; the actual amount depends on container size.)

• OpenSSH(if required for intended use). It can be downloaded from https://www.openssh.com/.

• Powershell script for image creation (vca_create_windows_image.ps1 from buildscripts/windows/windows_part in VCAC-R host SW package(VCAC-R Contents of the Release Package on page 22) (which also contains all other source files for Windows image generation, particularly the folder answer_files).
Creating Windows* Baremetal Images

Windows baremetal images are dedicated for BlockIO boot mode (default, persistent approach) or via KVM hypervisor. The `boot_part_type` parameter set should be set to GUID Partition Table (GPT) and can be used for BlockIO or KVM, Master Boot Record (MBR) for KVM or Xen.

Image Creation Script Parameters

- **-iso** – Path to Windows installation iso file.
- **-output_dir** – Directory which will contain compressed resulting img for VCA (if not specified, default directory name is `out`).
- **-mount_dir** – Directory to which `wim` file from windows installation iso will be mounted during image creation (if not specified, default directory name is `mount_dir`).
- **-tmp_dir** – Directory used for temporary files (if not specified, default directory name is `tmp`).
- **-driver_dir** – Directory containing VCA drivers (available with build release). This directory needs to contain the `Win8.1Release-x64` folder, as the folder name is hardcoded.
- **-vcagent_dir** – Directory containing VCAgent (available with build release). This directory should contain VCAgent.* files.
- **-answer_file** – Path to Windows answerfile (same as `unattend` file).
- **-dism_path** – Path to `dism` file (from Windows ADK).
- **-vca_image_version** – Added to resulting file name (default is `0.0.0`).
- **-gfx_drv_dir** – Optional. Path to directory containing Intel graphics driver.
- **-win_edition** – Windows edition to be incorporated into img file (for example ServerStandard, Enterprise or Windows 10 Pro).
- **-netkvm_drv_dir** – Optional. If image is going to be used on KVM, it specifies path to NetKVM driver directory (optional).
- **-xen_driver_dir** – Optional. If image is going to be used on Xen, it specifies path to Xen driver directory (containing XenBus, XenNet, and Xenvif) (optional).
- **-openssh_dir** – Optional. Path to OpenSSH installation files directory, if it is to be installed (optional). Hardcoded in `AutoUnattend.xml` file for `setupssh-7.4p1-1.exe`.
- **-virtualbox** – Path to `VBoxManage.exe` file.
- **-vhd_size** – Resulting image size in GB. Recommended minimum size is 15 GB.
- **-boot_part_type** – Type of created image. Only GPT (for BlockIO) is supported.
- **-zip_img** – Name of zip file containing resulting Windows image file (optional). Default is `vca_windows_baremetal.zip`. 
2.2.6.4 Creation of BlockIO/KVM Windows Images

Once all required software and files are present, image creation is quite straightforward. The script has to be executed with parameters specified above in Image Creation Script Parameters on page 28. It results in a zipped .img file created in the output directory. This file can be booted (depending on parameters provided) on BlockIO/KVM/Xen.

Directories tmp_dir, out_dir, and mount_dir can be specified on different drives (SSD or M.2) to speed up image building process. If not defined, they are created in the same directory in which the PowerShell script is executed.

An example use of the image building script is below:

```powershell
./vca_create_windows_image.ps1 -iso .\en_windows_server_2016_x64_dvd_9718492.iso -driver_dir .\VcaKmd\Win\Win8.1Release-x64 -vcagent_dir .\VCAgent -answer_file .\answer_files\WS2016\AutoUnattend.xml -gfx_drv_dir .\GFX_driver_20.19.15.4549_BDW_SKL -dism_path 'C:\Program Files (x86)\Windows Kits\10\Assessment and Deployment Kit\Deployment Tools\x64\DISM\dism.exe' -win_edition ServerStandard -virtualbox 'C:\Program Files\Oracle\VirtualBox\VBoxManage.exe' -vhd_size 11GB -boot_part_type GPT -xen_driver_dir .\Xen -openssh_dir .\OpenSSH -netkvm_drv_dir .\NetKVM\2k16 -tmp_dir d:\tmp -mount_dir d:\mount_dir -zip_img vca_windows_10_1803_baremetal_GPT.zip
```

2.2.6.5 Windows Image Resizing

If required, images or containers can be resized simply by running following command:

```
dd if=/dev/zero bs=1M count=4000 >> ./binary.img
```

The count parameter depends on the amount of space to be added. After resizing the file, the image should be booted and the disk resized normally in Windows disk manager using unallocated space.

2.2.7 Using VCAC-R System Image and Installation Package

This method requires that VCAC-R card is plugged in to the PCIe slot of the Intel® Xeon® Scalable Processor.

2.2.7.1 Setting up Intel® Xeon® Scalable Processor Server Host

- Install CentOS7.6 in host Intel® Xeon® Scalable Processor server
  (Optional with some types of Scalable Processor servers: If you see an error like "CPU #* stuck for ** seconds", try the following:
  Boot from USB drive, when you boot into install grub page, press Tab button, add "nomodeset" in grub command line)
- Disable SSC in BIOS (the menu path might be different in different BIOS):
  Advanced -> integrated IO Configuration I -> Pcie P11 SSC (set to Disable)
- Set proxy in host (Optional, depends on local network environment):

```
# vim /etc/yum.conf
export https_proxy="local network https proxy"
export http_proxy="local network http proxy"
```
export ftp_proxy="local network ftp proxy"

# vim /etc/apt.conf

Acquire::http::proxy "local network http proxy";
Acquire::https::proxy "local network https proxy";

# yum update

* Before installing the VCAC-R software package on host, check PCIe device availability through the following:

```bash
# lspci | grep PLX
af:00.0 PCI bridge: PLX Technology, Inc. Device 8733 (rev ca)
b0:08.0 PCI bridge: PLX Technology, Inc. Device 8733 (rev ca)
b0:09.0 PCI bridge: PLX Technology, Inc. Device 8733 (rev ca)

# lspci | grep 295
af:00.2 System peripheral: Intel Corporation Device 2952 (rev ca)
af:00.4 System peripheral: Intel Corporation Device 2952 (rev ca)
b1:00.0 Bridge: Intel Corporation Device 2954 (rev ca)
b2:00.0 Bridge: Intel Corporation Device 2955 (rev ca)
```

### 2.2.7.2 VCAC-R Software Installation on Host

Follow the steps below to install the VCAC-R software on host:

1. Copy the kernel and VCAC-R card driver package compiled in Build Host Kernel and VCAC-R Driver on page 26 to a temporary folder on the host server.

2. Install the kernel packages:

   ```bash
   #sudo yum -y localinstall kernel-3.10.0-957.el7.centos.2.7.363.VCA.x86_64.rpm
   #sudo yum -y localinstall kernel-devel-3.10.0-957.el7.centos.2.7.363.VCA.x86_64.rpm
   ```

3. Configure the new kernel to be the default at boot.

   **NOTE**

   This step is very important to boot the operating system with proper kernel.

   ```bash
   #sudo grub2-set-default 0
   ```

4. (Optional) If updating from a previous VCAC-R version, remove the older RPMs with the following command:

   ```bash
   #rpm -qa | grep -e daemon-vca -e vcass-modules | xargs yum -y erase
   ```

5. Install the VCAC-R driver and utility.

   ```bash
   #sudo yum -y localinstall vcass-modules-3.10.0-957.el7.centos.2.7.363.VCA.x86_64-2.7.363-0.x86_64.rpm
   #sudo yum -y localinstall daemon-vca-2.7.363-x86_64.rpm
   ```

6. Reboot the system to enable the new kernel.

   ```bash
   #sudo reboot
   ```
7. After reboot, confirm that the expected kernel on the host is being used.

   #uname -r 3.10.0-957.el7.centos.2.7.363.VCA.x86_64

### 2.2.7.3 Accessing VCAC-R Card via Host Using DHCP Setup

Following steps can be used to access the VCAC-R card via host using DHCP setup:

1. Stop Network Manager

   systemctl stop NetworkManager
   service NetworkManager stop

2. Create a bridge configuration file (e.g. `/etc/sysconfig/network-scripts/ifcfg-virbr0-vca`) containing the following lines:

   ```
   DEVICE=virbr0-vca
   TYPE=Bridge
   BOOTPROTO=dhcp
   ONBOOT=yes
   NM_CONTROLLED=no
   ```

3. Modify the main interface file (e.g. `/etc/sysconfig/network-scripts/ifcfg-enp3s0f0`) to contain the following lines. The main interface is the interface physically connected to the network.

   **NOTE**

   `enp3s0f0` is the main Network Interface, this name could change in every system.

   ```
   DEVICE=enp3s0f0
   TYPE=Ethernet
   BOOTPROTO=dhcp
   ONBOOT=yes
   NM_CONTROLLED=no
   BRIDGE=virbr0-vca
   UUID=UUID_OF_DEVICE
   ```

4. Restart the network.

   systemctl restart network

5. Configure Intel® VCAC-R nodes to use the new network bridge.

   `vcactl config bridge-interface virbr0-vca`

6. Increase the MTU size of the main network interface used.

   `ifconfig enp3s0f0 mtu 9000` (Note: replace `enp3s0f0` with main network interface name)

7. For DHCP configuration, use the following command:

   `vcactl config ip dhcp`
2.2.7.4 VCAC-R Card Boot up with vcad Image

Boot up the VCAC-R card with the Windows Image created before as in chapter Build Windows System Image for VCAC-R node on page 27 and in section Creation of BlockIO/KVM Windows Images on page 29:

- **Boot VCAC-R card**

  ```bash
  #vcactl blockio open 0 0 vcablk0 RW $PATH/vca_windows_10_1803_baremetal_GPT_2.6.265.img
  #vcactl boot 0 0 vcablk0
  ```

- **Check VCAC-R status:**

  ```bash
  #vcactl status
  ```

  If status is:

  ```bash
  Card: 0 Cpu: 0 STATE:link_down,
  ```

  Then try the steps below:

  ```bash
  #vcactl pwrbtn-long
  #vcactl pwrbtn-short
  ```

  Check the status again via:

  ```bash
  #vcactl status
  ```

  It should be in "bios_up".

  ```bash
  Card: 0 Cpu: 0 STATE: bios_up
  ```

  ```bash
  #vcactl reset 0 0 --force
  #vcactl boot 0 0 vcablk0
  #vcactl status
  Card: 0 Cpu: 0  STATE: net_device_ready
  ```

- **If the device status is ready, you can login into the VCAC-R card using its IP address.**

  Check IP address of the VCAC-R. Following is an example of one host connected with two VCAC-R cards:

  ```bash
  #vcactl network ip  0  0:
  172.33.1.1
  Card 1 Cpu 0:
  172.33.2.1
  ```

- **Login to VCAC-R Card 0 through RDP protocol/viewer.**

  Username: Administrator
  Password: vista12#
**2.2.8 PXE Feature Description**

PXE (Pre eXecution Environment) boot is a mechanism allowing to start an operating system from network, without any physical media attached to the computer. It is not unique to the VCA card - the protocols used by the feature are the same as the ones powering the process on a desktop or server PC.

**2.2.8.1 Usage on the Card**

The PXE boot feature allows booting the card via a virtual network card that appears on the host, separate from the one that is used by the running OS.

The workflow is as follows:

1. Prepare the PXE boot setup - network, images, servers, etc.
2. Enable the PXE virtual network card.
3. Configure the virtual network card using Linux tools (usually bridging it to another network).
4. Boot the system using PXE.

**2.2.8.2 Network Preparation**

The PXE boot feature uses DHCP extensively - the server hands out not only addresses, but also location of the bootloader. This makes use of static addressing impossible - if each node is to have a predetermined address, the DHCP server should be configured to hand out static IP addresses based on the client's MAC address.

Preparing the configuration depends on the server, as well as target node operating systems, and is not discussed in this manual - the setup does not differ from preparing for PXE booting an ordinary machine.

**2.2.8.3 Limitations and Precautions**

Since there is no way to interact with the software running on the card before operating system boots, the boot process has to be non-interactive.

The recommended way to boot Windows is to:

1. serve the image via iSCSI
2. use iPXE open source software to boot over iSCSI – the supported version is the **SNP only version**

The network configuration for the booted OS (usually) has to match the configuration used in PXE boot.

**2.2.8.4 vcactl Commands Reference**

**2.2.8.4.1 Enable the PXE Network Card**

```
# vcactl pxe enable
```

Executing this command creates PXE boot network cards, one for each node, named `vcapxe<card><node>`. Note that interfaces are not configured and down by default.
If activation for only one node is desired, it can be done by specifying it on the command line, for example, to enable PXE for card 0, node 2:

```
# vcactl pxe enable 0 2
```

### 2.2.8.4.2 Disable the PXE Network Card

```
# vcactl pxe disable
```

This command is used to remove the PXE boot network cards. Note that if PXE boot was initiated and it has not finished, either by a success or choosing another boot method, it won't be possible to withdraw the interface, as it will be in use.

### 2.2.8.4.3 List the PXE Network Card Status

```
# vcactl pxe status
vcapxe00        Active
vcapxe01        Inactive
vcapxe02        Active
```

Lists the status of each network card:

- **Inactive** means that the PXE boot is completely disabled. The dedicated interface is not visible, and the card can't be booted using PXE.
- **Active** means that the interface is visible and can be configured, or disabled if not needed. Appropriate command will trigger the PXE boot process.
- **In use** means that the node is right now using the interface in its boot process.

### 2.2.8.4.4 Boot Using PXE

```
# vcactl boot vcapxe
```

Boots the card using previously enabled and configured interface (see Enable the PXE Network Card on page 33). If only one node is to be booted, it can be done, for example to boot card 0, node 2:

```
# vcactl boot 0 2 vcapxe
```

## 2.3 Additional Specific Software Requirements

*Cloud Gaming For Windows* solution needs proper graphics drivers to work properly. The two graphics adapters are from Intel and AMD. Proper version of these graphics drivers are as follows:

1. Intel® HD Graphics 630 driver (proper version 25.20.100.6373) - https://downloadmirror.intel.com/28289/a08/win64_25.20.100.6373.exe

This release of the *Cloud Gaming For Windows* is dedicated for Windows 10 OS. Resources mentioned below are required to build and run it.

**Required to build and run:**
- Microsoft Visual Studio 2017 (Windows SDK version: 10.0.17763.0)
- Vulkan® SDK version 1.1.114.0 - https://vulkan.lunarg.com/sdk/home#sdk/downloadConfirm/1.1.114.0/windows/VulkanSDK-1.1.114.0-Installer.exe
- Chrome browser and additional proxy settings if needed.
- FFmpeg binaries (supported version 4.1.4):
  - Shared - https://ffmpeg.zeranoe.com/builds/win64/shared/ffmpeg-4.1.4-win64-shared.zip
  - Dev - https://ffmpeg.zeranoe.com/builds/win64/dev/ffmpeg-4.1.4-win64-dev.zip
- EasyHook binaries (supported version 2.7) - https://github.com/EasyHook/EasyHook/releases/tag/v2.7.6789.0

Required to run only:
- Microsoft Visual C++ Redistributable for Visual Studio 2010
  - x64 - https://download.microsoft.com/download/3/2/2/3224B87F-CFA0-4E70-BDA3-3DE650EFEBA5/vcredist_x64.exe
- Microsoft Visual C++ Redistributable for Visual Studio 2017
  - x86 - https://aka.ms/vs/16/release/vc_redist.x86.exe
  - x64 - https://aka.ms/vs/16/release/vc_redist.x64.exe
- Vulkan® SDK version 1.1.114.0 - https://vulkan.lunarg.com/sdk/home#sdk/downloadConfirm/1.1.114.0/windows/VulkanSDK-1.1.114.0-Installer.exe
- Chrome Browser.
- FFmpeg binaries (supported version 4.1.3):
  - Shared - https://ffmpeg.zeranoe.com/builds/win64/shared/ffmpeg-4.1.3-win64-shared.zip
  - Dev - https://ffmpeg.zeranoe.com/builds/win64/dev/ffmpeg-4.1.3-win64-dev.zip
- EasyHook binaries (supported version 2.7) - https://github.com/EasyHook/EasyHook/releases/tag/v2.7.6789.0

2.4 List of Modules

Cloud Gaming For Windows solution contains following projects:
- asource-system – audio initialization and configuration
- CloudGamingForWindows – bundle of installers
- CloudGamingForWindowsInstaller – main installer of components
- ctr-sdl – sdl events handling
• **download-extra-elements** – download 3rd party component as FFmpeg and EasyHook
• **encoder-audio** – audio encoding handling
• **encoder-mxf** – video encoder handling
• **filter-rgb2yuv** – screen image processing
• **ga-client** – client related components
• **ga-hook** - additional GFX API calls hooking mechanism implementation
• **ga-server-event-driven** – run media server and start injecting into game process
• **ga-server-manager** – Main application, run server and wait for response from client
• **gpa-hook** – main GFX API calls hooking mechanism implementation
• **libga** – processing components, configurations, loading modules
• **live555-adapter** – make dll from static libraries of live555 streaming media
• **server-live555** – live555 media server related components

### 2.5 Automatic Environment Configuration

Environment configuration for *Cloud Gaming For Windows* can be done via two methods. First (preferred) method is to automatically configure the environment using an installer utility (*CloudGamingForWindows.exe* from VCAC-R Contents of the Release Package on page 22). Installer requires internet access to work properly. Second method is to manually configure the environment as described in Manual Environment Configuration on page 45.

Step by step instructions on how to set up environment with installer are described below:

**NOTE**
Chrome Browser should be installed on the machine as a pre-requisite. The executable file needs Internet Access via chrome.

1. **Agree to License Terms and Conditions**

The first step is to agree to the license terms and conditions which are required to proceed with the installation. Agreeing to install external (or 3rd Party) components is optional but these files are necessary for proper working of the environment. After checking all agreements, click ”Install”.
2. Processing: Installation of components from the Web

"Processing" is the stage where all necessary components are getting installed from the Web. It may take some time. Following screen shows this step:

3. Main Component Installer

The initial window of the main component installer for Cloud Gaming for Windows is shown in the following image. Read the information and click "Next".
4. License Agreement of Cloud Gaming for Windows Setup

This section is dedicated to the License agreement of the main component. Select checkbox "I accept the terms in the License Agreement" and then click "Next".
5. Custom Setup: Choose Components for Installation

In this section, user can choose which components to install on the machine. There are three options:

- Cloud Gaming For Windows Server – binaries required to run Server side
- Cloud Gaming For Windows Client – binaries required to run Client side
- Cloud Gaming For Windows Development Environment - preparing environment for developers
Once selections are made, click "Next".

6. Last screen for Processing Installation

The following screen appears and user can click on the “Install” button to start installation.
A new screen appears which updates the status of installation.
7. Downloading Additional Components

This part is responsible for downloading additional components such as FFmpeg and EasyHook from the Web (only if user agreed to download them). User does not have to do anything additional here. These components are required by the environment but not distributed.
8. Successful Installation of Main Component

The last screen shows that set up of Cloud Gaming for Windows is completed successfully. User can click on “Finish” button.
9. Installation of Intel® Media SDK component

Intel® Media SDK component will start getting installed automatically.
After installation with installer, user will have to install Microsoft Visual Studio 2017 or Microsoft Visual C++ Redistributable for Visual Studio 2010 and Microsoft Visual C++ Redistributable for Visual Studio 2017 (depends if user chooses runtime environment or development environment). The links are given in Additional Specific Software Requirements on page 34.

2.6 Manual Environment Configuration

If a user chooses to configure the environment manually, steps are described below:

1. Install MS Visual Studio 2017
2. Install Intel Media SDK 2018 R2
3. Install Vulkan® SDK version 1.1.114.0 - https://vulkan.lunarg.com/sdk/home/sdk/downloadConfirm/1.1.114.0/windows/VulkanSDK-1.1.114.0-Installer.exe
5. Download all required external resources and place them in proper directories:
   a. Static libraries (FFmpeg and EasyHook) files (.lib) should be placed in:
      • deps.win64->lib (for 64 bit version of files)
      • deps.win32->lib (for 32 bit version of files)
   b. Header files (.h) should be placed in:
• FFmpeg:
  — deps.win64->include->ffmpeg (for 64 bit version of files)
  — deps.win32->include->ffmpeg (for 32 bit version of files)

• EasyHook:
  — deps.win64->include->easylhook (for 64 bit version of files)
  — deps.win32->include->easylhook (for 32 bit version of files)

  c. Executable files (.exe) and dynamic linked libraries files (.dll) should be placed in:
  • FFmpeg:
    — deps.win64->bin->ffmpeg (for 64 bit version of files)
    — deps.win32->bin->ffmpeg (for 32 bit version of files)
  • EasyHook:
    — deps.win64->bin->easylhook (for 64 bit version of files)
    — deps.win32->bin->easylhook (for 32 bit version of files)

2.7 Build

Build process is executed by MS Visual Studio 2017. To perform it, user should open GamingAnywhere.sln solution. IDE should allow to build x64 configuration only (in case of manual environment configuration, it should be possible to build Win32 configuration also). To build, click “select build configuration” e.g.:

Figure 2. Build Configuration

Then click "Build->Build Solution."

Build results should be divided into client and server side. Installer is independent from client and server.

2.8 Run Game Server

If environment configuration was done automatically, there are two methods of launching Cloud Gaming For Windows server. First method is to launch using icon placed in the Start menu. There are separate icons for client and server.
Second method is to run *Cloud Gaming For Windows* server via command line shell.

To run *Cloud Gaming For Windows* game server, open Windows command line shell and navigate to the folder with server binaries:

**Example:**

```bash
C:\ >cd <path_to_the_server_bin_folder>
```

Next, ensure `ga-server-manager.exe` file and other binaries are present in that folder.

Then execute `ga-server-manager.exe` file. This creates a process which waits for request from client to launch the selected game. When client sends a request, chosen game will be made to run.

To launch server with optional configuration file, following command line should be executed:

```bash
C:\\<path_to_the_server_bin_folder>ga-server-manager.exe <optional_path_to_conf_file>
```

`<optional_path_to_conf_file>` - path to the server configuration file.

If `ga-server-manager.exe` is run without `<optional_path_to_conf_file>` parameter, application will get default configuration file which is placed in `config` subdirectory in the directory with binaries.

**NOTES**

- Before starting *Cloud Gaming For Windows* game server, make sure that process which will be run by *Cloud Gaming For Windows* is not running already.
- The server configuration file needs to be modified to point to the location of executable game file - `Game.exe` (it can be any game that user intends to run).
2.9 Run Client

Same as in case of server, if environment configuration was done automatically, there are two methods of launching Cloud Gaming For Windows client. First method is to launch the client using icon placed in the Start menu. There are separate icons for client and server.

Figure 4. Start Menu-icon

Second method is to run Cloud Gaming For Windows client via command line shell.

To run Cloud Gaming For Windows client, run Windows command line shell and navigate to the folder with client binaries:

```
C:\>cd <path_to_the_client_bin_folder>
```

Next, ensure `ga-client.exe` file and other binaries are present in that folder.

Then launch `ga-client.exe` file, which sends request to the server. After sending request, client waits for some time and tries to connect to the running game.

**NOTE**
Before running the client, set proper IP address of the server in the configuration file.

To launch client, following command line should be executed:

```
C:\<path_to_the_client_bin_folder>ga-client.exe <optional_path_to_conf_file>
```

`<optional_path_to_conf_file>` - path to the client configuration file.

If `ga-client.exe` is run without `<optional_path_to_conf_file>` parameter, application will get default configuration file which is placed in `config` subdirectory in the directory with binaries.
NOTE
If client doesn't connect to the game, try to run ga-client.exe one more time. Problem could be caused by above average game launching time.

2.10 E2E Latency Measurement

The software has an option to enable end-to-end latency measurement, that is, time that elapses between hypothetical user action and the display time of first frame in which the effect of the action could be observed. To enable this, in the client configuration file, find a line looking like:

```plaintext
latency-measurement = false
```

and change it to:

```plaintext
latency-measurement = true
```

NOTE
No server configuration change is required.

The latency (in milliseconds) will be displayed in top-left corner of the screen when in-game. Measurement results can be saved to a text file. In the client configuration file, uncomment the latency-measurement-log line, and provide the name of the file to which results will be logged:

```plaintext
#latency-measurement-log = filename
```

and change it to:

```plaintext
latency-measurement-log = C:\Users\Gamer\Desktop\latency.log
```

NOTE
To use this feature, the latency measurement switch described above must be turned on.
Appendix A Intel® VCA Utility (vcact1)

A.1 Introduction to vcact1

The vcact1 utility allows the user to interact with the Intel® VCA card and nodes. To execute the utility, the user must be either a member of the special group vcausers, which is created during utility installation; a member of the sudoers group (that is, they must have sudo privileges on the system); or a user with root privileges. In the first and last cases (a member of vcausers or a root user), no extra commands must be typed. In the second case (a member of the sudoers group), all commands must be prepended by sudo (sudo followed by a space character).

To add a user to the vcausers group, use the following command as either root or a root-privileged user (e.g., a sudoers user using sudo):

```
usermod -aG vcausers <username>
```

NOTE
To add a username to vcausers, a relgin or reboot is required.

A.2 vcactl Usage

Use the following syntax and structure to use the vcactl utility.

```
vcactl [execution_mode] command [subcommand] [card_id [cpu_id]] [command_params]
```

The available execution modes are:

- `v`: log verbose level set to DEBUG
- `vv`: log verbose level set to FULL-INFO
- `--skip-modprobe-check`: turn off checking whether vca device is ready
- `--force`: force command execution (WARNING: you do it at your own risk!)
A.3 Command Line Reference

A.3.1 vcactl help

A.3.1.1 Usage

vcactl help

A.3.1.2 Description

Prints out help information about how to use vcactl.

```
Usage:
    vcactl [execution_mode] command [subcommand] [card_id] [cpu_id] [command_params]

Available execution modes:
- m: log verbose level set to DEBUG
- w: log verbose level set to FATAL

--skip-mode-check: turn off checking whether a device is ready
--force: force command execution (WARNING: you do it at your own risk)

Available commands are:
  status: check status of the CPU
  reset: resets the CPU
  wait-BIOS: waits for CPU to be ready on desired card and CPU.

If no target path is provided, configuration field 'on-image' is used.
If no target path is provided, configuration field 'last-on-image' or 'on-image' is used.

update-BIOS: allows configuration update for the CPU.
recovery-BIOS: allows configuration update for the CPU.
```

A.3.2 vcactl wait-BIOS

A.3.2.1 Usage

vcactl wait-BIOS [card_id] [cpu_id]

A.3.2.2 Description

Waits for CPU <card_id> [cpu_id] to enter BIOS is up and running mode, typically used after host reboot or vcactl reset command. <cpu_id> is optional. Reports an error if CPU cannot enter BIOS is up and running mode.

```
#vcactl wait-BIOS
Card: 1 Cpu: 0 - BIOS is up and running!
Card: 0 Cpu: 1 - BIOS is up and running!
Card: 0 Cpu: 0 - BIOS is up and running!
Card: 1 Cpu: 1 - BIOS is up and running!
```

A.3.3 vcactl status

A.3.3.1 Usage

vcactl status [card_id] [cpu_id]
A.3.3.2 Description

Reads the status of the CPUs in the system. Normally this command should return bios_up. Use `<card id>` to read all CPUs on the specified card. Use `<card id> [<cpu id>]` to read the status of the specified CPU. `<cpu id>` is optional.

```
# vcactl status
Card: 0 Cpu:0 STATE: bios_up
Card: 0 Cpu:1 STATE: bios_up
Card: 1 Cpu:0 STATE: bios_up
Card: 1 Cpu:1 STATE: bios_up
```

A.3.3.3 Result

Table 7. Possible Results for vcactl status

<table>
<thead>
<tr>
<th>Result</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>link_down</td>
<td>if card CPU is down due to any reason if CPU link to PLX is down (usually means that PLX eprom is invalid)</td>
</tr>
<tr>
<td>power_off</td>
<td>if card CPU is switched off or shutdown</td>
</tr>
<tr>
<td>powering_down</td>
<td>If card CPU is shutting down</td>
</tr>
<tr>
<td>bios_down</td>
<td>CPU BIOS failed upon initialization or still booting (usually when memory training fails such state is reported).</td>
</tr>
<tr>
<td>bios_up</td>
<td>Link is up and BIOS is ready for handshake.</td>
</tr>
<tr>
<td>bios_ready</td>
<td>Handshake has succeeded with BIOS.</td>
</tr>
<tr>
<td>bios_done</td>
<td>BIOS is in a temporary state after allocating resources for completing the operation.</td>
</tr>
<tr>
<td>flashing</td>
<td>BIOS is being updated.</td>
</tr>
<tr>
<td>booting</td>
<td>OS is being booted.</td>
</tr>
<tr>
<td>drv_probe_done</td>
<td>Main PCIe* driver has been loaded.</td>
</tr>
<tr>
<td>drv_probe_error</td>
<td>Main PCIe* driver couldn’t be loaded.</td>
</tr>
<tr>
<td>dhcp_in_progress</td>
<td>Card is obtaining IP address from DHCP.</td>
</tr>
<tr>
<td>dhcp_done</td>
<td>Card obtained IP address from DHCP.</td>
</tr>
<tr>
<td>dhcp_error</td>
<td>Card could not obtain IP address from DHCP.</td>
</tr>
<tr>
<td>nfs_mount_done</td>
<td>Card mounted NFS resources.</td>
</tr>
<tr>
<td>nfs_mount_error</td>
<td>Card could not mount NFS resources.</td>
</tr>
<tr>
<td>os_ready</td>
<td>OS boot completed.</td>
</tr>
<tr>
<td>net_device_up</td>
<td>Intel® VCA network stack is up but OS is not yet loaded.</td>
</tr>
<tr>
<td>net_device_down</td>
<td>Intel® VCA network stack has been switched off.</td>
</tr>
<tr>
<td>net_device_ready</td>
<td>Intel® VCA network stack is up, OS is booted, and IP address is assigned.</td>
</tr>
<tr>
<td>net_device_no_ip</td>
<td>Intel® VCA network stack is up and OS is booted, but IP address is not assigned (for example, DHCP response has been not received).</td>
</tr>
<tr>
<td>resetting</td>
<td>Intel® VCA CPU is being reset.</td>
</tr>
<tr>
<td>error</td>
<td>Error occurred different than the specific errors listed above.</td>
</tr>
</tbody>
</table>
A.3.4 vcactl update-BIOS

A.3.4.1 Usage
vcactl update-BIOS [<card_id> [<cpu_id>]] <biosImageFile>

A.3.4.2 Description
Updates BIOS (flash SPI user BIOS partition) on specified CPU(s) in the system. Before running this command, CPUs must be in the bios_up or bios_ready state. (Use vcactl reset and vcactl wait-BIOS to force CPUs to enter the bios_up state.) Host reboot is not required after vcactl update-BIOS.

G3 (mechanical off) is required after vcactl update-BIOS. (To perform G3, execute the power off command on the host and then disconnect from the power supply for 15 seconds.)

# vcactl status
Card: 0 Cpu:0 STATE: bios_up
Card: 0 Cpu:1 STATE: bios_up
Card: 1 Cpu:0 STATE: bios_up
Card: 1 Cpu:1 STATE: bios_up

A.3.4.3 Result
The CPU status transitions from bios_up or bios_ready to flashing and completes in the bios_ready state. A temporary state of bios_done may be reported, as well.

If there is a failure, an error status is reported (via the vcactl status command).

A.3.5 vcactl recover-BIOS

A.3.5.1 Usage
vcactl recover-BIOS [<card_id> [<cpu_id>]] <biosImageFile>

A.3.5.2 Description
Updates BIOS via the Gold BIOS image. Use when in need of recovery. Before running this command, the Intel® VCAC-R nodes must be in the bios_up state. This command may take much longer than the standard BIOS update.

A.3.6 vcactl update-EEPROM

A.3.6.1 Usage
vcactl update-EEPROM [<card_id>] <eepromImageFile>

NOTE
This command should be executed as root.
### A.3.6.2 Description

Updates PCIe* firmware on all Intel® VCA cards or on the specified card. After successful completion of the command, the host system is reboot to work with the new firmware on the card. This command requires root privileges. The Intel® VCA nodes must be in the bios_up state before running this command.

```bash
# vcactl status
Card: 0 Cpu:0 STATE: bios_up
Card: 0 Cpu:1 STATE: bios_up
Card: 1 Cpu:0 STATE: bios_up
Card: 1 Cpu:1 STATE: bios_up

# vcactl update-EEPROM eeprom_8183ffee.bin
EEPROM update started!
Update EEPROM process started (for card 0). Do not power down system!
Update EEPROM for first PCIe switch successful!
Update EEPROM successful (for card 0). Reboot system is required to reload EEPROM.
EEPROM update started!
Update EEPROM process started (for card 1). Do not power down system!
Update EEPROM for first PCIe switch successful!
Update EEPROM successful (for card 1). Reboot system is required to reload EEPROM.
```

### Result

The EEPROMs on the card(s) are updated upon successful completion, at which point a reboot of the system is required.

If there is a failure, an error status is reported after completion of the command. In these circumstances, a retry of the update is strongly recommended prior to any reboot; otherwise, the card may be damaged.

### A.3.7 vcactl reset

#### A.3.7.1 Usage

`vcactl reset [<card_id> [cpu_id]]`

#### A.3.7.2 Description

Resets the specified CPUs to bios_up state. Run vcactl wait-BIOS after vcactl reset to wait for vcactl reset to complete. Normally, the CPUs should enter the BIOS is up and running mode.

```bash
# vcactl reset
# vcactl wait-BIOS
Card: 0 Cpu:0 STATE: BIOS is up and running
Card: 0 Cpu:1 STATE: BIOS is up and running
Card: 1 Cpu:0 STATE: BIOS is up and running
Card: 1 Cpu:1 STATE: BIOS is up and running
```
A.3.8 vcactl boot

A.3.8.1 Usage

vcactl boot [<card_id> [<cpu_id>]] [os_image_file.img|vcablk0
(for vca-disk)]

A.3.8.2 Description

Boots the operating system via Leverage Boot Protocol. Image is from the default
location (see the vcactl config os-image command in section vcactl config on
page 60) or from the image file specified in the command. The command requires
that the card CPU is in the bios_up or bios_ready state. Use vcactl wait to
wait for the completion of the vcactl boot command.

NOTE

For booting via blockio (vcablk0 parameter), there is a need to open it first, and add
reference to vcactl blockio open subcommand.

It is possible to use the last-os-image field as a parameter to boot.

```
#vcactl boot vca_baremetal_4p4_centos7.2_1.5.174.img
#vcactl wait
Card: 0 Cpu:0 STATE: Net device ready!
Card: 0 Cpu:1 STATE: Net device ready!
Card: 1 Cpu:0 STATE: Net device ready!
Card: 1 Cpu:1 STATE: Net device ready!
```

A.3.8.3 Result

During the OS boot, the reported state is booting (the bios_done state may be
visible, also). On successful completion, each CPU is in the net_device_ready state.
If there is a failure, the specific error cause is reported (via the vcactl status
command) as one of drv_probe_error, dhcp_error, nfs_mount_error,
net_device_no_ip, or generic error.

A.3.9 vcactl reboot

A.3.9.1 Usage

vcactl reboot [<card_id> [<cpu_id>]] [os_image_file.img]

A.3.9.2 Description

Reboots the OS (resets the CPU and boots the selected OS) from the host via
Leverage Boot Protocol. Image is from the default location (see the vcactl config
os-image command in section vcactl config on page 60) or from the image file
specified in the command. The image file should have group access set to vcausers, otherwise wait will give TIMEOUT. Use `vcactl wait` to wait for the completion of the `vcactl boot` command.

```bash
#vcactl reboot
#vcactl wait
Card: 0 Cpu:0 STATE: Net device ready!
Card: 0 Cpu:1 STATE: Net device ready!
Card: 1 Cpu:0 STATE: Net device ready!
Card: 1 Cpu:1 STATE: Net device ready!
```

### A.3.9.3 Result

During the OS boot, the reported state is `link_down`, `dio_down`, `bios_up`, `bios_ready`, `booting`, `net_device_up`, `dhcp_in_progress`, or `os_ready` (the `bios_done`, `mod_probe_done`, `dhcp_done`, and `nfs_mount_done` states may be visible for a short time, also). On successful completion, each CPU is in the `net_device_ready` state. If there is a failure, the specific error cause is reported (via the `vcactl status` command) as one of `drv_probe_error`, `dhcp_error`, `nfs_mount_error`, `net_device_no_ip`, or `generic error`.

### A.3.10 vcactl wait

#### A.3.10.1 Usage

`vcactl wait [<card_id> [<cpu_id>]]`

#### A.3.10.2 Description

Waits until the OS boot is completed on the specified CPUs. This command is typically used after `vcactl boot` or `vcactl reboot` to report booting status.

#### A.3.10.3 Result

The command completes when the OS boot is done; otherwise, it is blocking. On successful boot, all CPUs finish in the `net_device_ready` state. If there is a failure, the specific error cause is reported as one of `drv_probe_error`, `dhcp_error`, `nfs_mount_error`, `net_device_no_ip`, or `generic error`.

### A.3.11 vcactl temp

#### A.3.11.1 Usage

`vcactl temp [<card_id> [<cpu_id>]]`

#### A.3.11.2 Description

Retrieves the temperature of one or more CPUs in the system. If no card or CPU is specified, the command returns the temperature of all nodes on all cards.
A.3.11.3 Result

The current card output temperature and the node processor temperatures are reported for each card.

```
[root@vcademo VCA_1.2.81]# vcactl temp
Card 0 Cpu 0:
coretemp-isa-0000
Adapter: ISA adapter
Physical id 0: +69.0°C (high = +105.0°C, crit = +105.0°C)
Core 0: +67.0°C (high = +105.0°C, crit = +105.0°C)
Core 1: +66.0°C (high = +105.0°C, crit = +105.0°C)
Core 2: +67.0°C (high = +105.0°C, crit = +105.0°C)
Core 3: +67.0°C (high = +105.0°C, crit = +105.0°C)
Card 0 Cpu 1:
coretemp-isa-0000
Adapter: ISA adapter
Physical id 0: +72.0°C (high = +105.0°C, crit = +105.0°C)
Core 0: +70.0°C (high = +105.0°C, crit = +105.0°C)
Core 1: +69.0°C (high = +105.0°C, crit = +105.0°C)
Core 2: +69.0°C (high = +105.0°C, crit = +105.0°C)
Core 3: +69.0°C (high = +105.0°C, crit = +105.0°C)
Card 0 Cpu 2:
coretemp-isa-0000
Adapter: ISA adapter
Physical id 0: +78.0°C (high = +105.0°C, crit = +105.0°C)
Core 0: +77.0°C (high = +105.0°C, crit = +105.0°C)
Core 1: +77.0°C (high = +105.0°C, crit = +105.0°C)
Core 2: +76.0°C (high = +105.0°C, crit = +105.0°C)
Core 3: +76.0°C (high = +105.0°C, crit = +105.0°C)
Card 1 Cpu 0:
coretemp-isa-0000
Adapter: ISA adapter
Physical id 0: +56.0°C (high = +105.0°C, crit = +105.0°C)
Core 0: +56.0°C (high = +105.0°C, crit = +105.0°C)
Core 1: +54.0°C (high = +105.0°C, crit = +105.0°C)
Core 2: +55.0°C (high = +105.0°C, crit = +105.0°C)
Core 3: +55.0°C (high = +105.0°C, crit = +105.0°C)
Card 1 Cpu 1:
coretemp-isa-0000
Adapter: ISA adapter
Physical id 0: +56.0°C (high = +105.0°C, crit = +105.0°C)
Core 0: +56.0°C (high = +105.0°C, crit = +105.0°C)
Core 1: +54.0°C (high = +105.0°C, crit = +105.0°C)
Core 2: +55.0°C (high = +105.0°C, crit = +105.0°C)
Core 3: +55.0°C (high = +105.0°C, crit = +105.0°C)
Card 1 Cpu 2:
coretemp-isa-0000
Adapter: ISA adapter
Physical id 0: +64.0°C (high = +105.0°C, crit = +105.0°C)
Core 0: +63.0°C (high = +105.0°C, crit = +105.0°C)
Core 1: +63.0°C (high = +105.0°C, crit = +105.0°C)
Core 2: +63.0°C (high = +105.0°C, crit = +105.0°C)
Core 3: +63.0°C (high = +105.0°C, crit = +105.0°C)
```
A.3.12  vcactl blockio open

A.3.12.1  Usage

```
vcactl blockio open <card_id> <cpu_id> [vcablk<N>] [[RO|RW <file_path>]|[ramdisk <size_mb>]]
```

where \(0 \leq N < 8\).

A.3.12.2  Description

Opens block IO device.

A.3.12.3  Examples

```
vcactl blockio open 0 1 vcablk3 ramdisk 20
vcactl blockio open 0 1 vcablk3 RO ~/disk.img
```

A.3.13  vcactl blockio list

A.3.13.1  Usage

```
vcactl blockio list <card_id> <cpu_id>
vcactl blockio list <blockio_id>
```

A.3.13.2  Description

Lists block IO devices.

A.3.14  vcactl blockio close

A.3.14.1  Usage

```
vcactl blockio close [<card_id>] [<cpu_id>] [vcablk<N>]
```
where $0 \leq N < 8$.

### A.3.14.2 Description

Closes block IO device.

### A.3.14.3 Examples

```bash
vcactl blockio close 0 1 vcablk3
vcactl blockio close vcablk0
```

### A.3.15 vcactl network

#### A.3.15.1 Usage

```bash
vcactl network <subcommand> [<card_id> [<cpu_id>]]
```

#### A.3.15.2 Description

Reads current network configuration of the card CPU to learn the IP address assigned by DHCP and the MAC addresses of the network interfaces of the Dom0 OS and DomU OS. The subcommands are the following and work on all or on the specified node:

- **ip** – Displays IP address of the (specified) node’s eth0 interface.
- **ip6** – Displays IP v6 address of the (specified) node’s eth0 interface.
- **mac** – Displays MAC address of the (specified) node’s eth0 interface so that user may configure DHCP server with that information.
- **vm-mac** – Displays MAC address of the DomU virtual network interface of the (specified) node’s so that DHCP server can be set accordingly.
- **all** – Displays all information of the (specified) node’s eth0 interface.
- **stats** – Displays statistics of the (specified) node’s eth0 interface.
- **dhcp-renew** – Forces renewal of DHCP address for (specified) nodes.

### A.3.16 vcactl ICMP-watchdog

#### A.3.16.1 Usage

```bash
vcactl ICMP-watchdog <1/0> [<card_id> [<cpu_id>] [<ip_address>]]
```

#### A.3.16.2 Description

Enables (1) or disables (0) ICMP watchdog service on the host that pings the specified node. The ICMP ping address is selected according to the current configuration. Optionally, the command may explicitly specify the IP address, so that the command can be used to monitor DomU activity.
A.3.17  vcactl update-MAC

A.3.17.1  Usage

`vcactl update-MAC <card_id> <cpu_id> <macAddressCanonical>`

A.3.17.2  Description

Updates MAC address (flash SPI GBE partition) on the specified CPU in the system. `card_id` and `cpu_id` are mandatory parameters for this command.

Command should be executed only in `bios_up` or `bios_ready` state.

A.3.17.3  Result

Status of the CPU transitions from `bios_up` or `bios_ready` to flashing and completes in the `bios_ready` state. If there is a failure, an error status is reported (via the `vcactl status` command).

A.3.18  vcactl script

A.3.18.1  Usage

`vcactl script [<card_id> [<cpu_id>]] <scriptFile>`

A.3.18.2  Description

Configures a bash script for the card CPU to perform Linux user-specific configuration that might be any configuration action such as:

- IP address assignment per virtIO interface or enabling the DHCP client
- Starting DomU guest OS

A.3.19  vcactl config

A.3.19.1  Usage

`vcactl config [<card_id> <cpu_id>] <parameter-name> <parameter-value>`

The available options and settings are listed in the table below:

<table>
<thead>
<tr>
<th>Parameter Name</th>
<th>Available Values</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>auto-boot</td>
<td>1 - enable, 0 - disable</td>
<td>Enable/disable auto booting. Note that for auto-boot to work, the directory containing the boot image and all its parent directories must either be world-readable or be owned by the vcausers group.</td>
</tr>
<tr>
<td>debug-enabled</td>
<td>1 - enable, 0 - disable</td>
<td>Enable/disable debug commands.</td>
</tr>
</tbody>
</table>

Table 8. vcactl config parameters

Continued...
<table>
<thead>
<tr>
<th>Parameter Name</th>
<th>Available Values</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>link-up-timeout-ms</td>
<td># of milliseconds</td>
<td>Set timeout for link-up after reset in milliseconds. Default is 2000\nmilliseconds (2 seconds)</td>
</tr>
<tr>
<td>handshake-irq-timeout-ms</td>
<td># of milliseconds</td>
<td>Set timeout for link-up after reset in milliseconds. Default is 30000\nmilliseconds (30 seconds).</td>
</tr>
<tr>
<td>alloc-timeout-ms</td>
<td># of milliseconds</td>
<td>Set timeout for RAMDISK allocation in BIOS. Default 100 is milliseconds.</td>
</tr>
<tr>
<td>cmd-timeout-ms</td>
<td># of milliseconds</td>
<td>Set timeout for LBP command reaction in BIOS. Default is 1000\nmilliseconds.</td>
</tr>
<tr>
<td>mac-write-timeout-ms</td>
<td># of milliseconds</td>
<td>Set timeout for MAC update command processing time in BIOS. Default 1000\nmilliseconds.</td>
</tr>
<tr>
<td>default-daemon-script</td>
<td>Name and path to\ndaemon script file</td>
<td>Name and path to daemon script file that is executed upon watchdog expiration.</td>
</tr>
<tr>
<td>wait-cmd-timeout-s</td>
<td># of seconds</td>
<td>Set timeout for WAIT command in vcactl (time needed to boot OS up).\nDefault is 160 seconds.</td>
</tr>
<tr>
<td>wait-bios-cmd-timeout-s</td>
<td># of seconds</td>
<td>Set timeout for WAIT-BIOS command in vcactl for BIOS UP time needed.\nDefault is 300 seconds.</td>
</tr>
<tr>
<td>wait-bios-cmd-flashing-s</td>
<td># of seconds</td>
<td>Set timeout for WAIT-BIOS command in vcactl for completion of BIOS\nupdate. Default is 1200 seconds.</td>
</tr>
<tr>
<td>ICMP-ping-interval-s</td>
<td># of seconds</td>
<td>Set ICMP watchdog period. Default is 1 second.</td>
</tr>
<tr>
<td>ICMP-response-timeout-s</td>
<td># of seconds</td>
<td>Set ICMP response timeout. Default is 10 second.</td>
</tr>
<tr>
<td>va-min-free-memory-enabled</td>
<td>1 – enable, 0 –\ndisable</td>
<td>Enable/disable minimum value (512 MB) of non-cached memory by Linux\nOS filesystem. This ensures that there will be enough free space to allocate\nbuffers needed by virtual network over PCIe*. Option refers to host\nsystem.</td>
</tr>
</tbody>
</table>

**Per card node options**

<table>
<thead>
<tr>
<th>os-image</th>
<th>Path to image</th>
<th>Path to bootable OS image</th>
</tr>
</thead>
<tbody>
<tr>
<td>last-os-image</td>
<td>Path to image (not\nuser-configurable)</td>
<td>Shows last booted image on node</td>
</tr>
<tr>
<td>script</td>
<td>Path to script</td>
<td>Path and script file name that is executed on card after OS image has been\nbooted successfully.\n/etc/vca_config.d/vca_&lt;slot_id&gt;&lt;cpu_id&gt;_default.sh</td>
</tr>
<tr>
<td>daemon-script</td>
<td>Path to script</td>
<td>Name and path to daemon script file that is executed upon watchdog expiration.</td>
</tr>
<tr>
<td>ip</td>
<td>IP address or dhcp</td>
<td>Set the node IP address or enable DHCP operation. Default is\n172.31.&lt;slot_id * 3 + cpu_id + 1&gt;.1.\nTo enable DHCP (since Intel® VCA Software Release 1.2.) for automatic IP\naddress assignment, set to dhcp. Enabling DHCP is allowed only if the node\nis already added to an existent bridge interface.</td>
</tr>
<tr>
<td>mask</td>
<td># of bits</td>
<td>Set mask length in bits. Default is 24 bits.</td>
</tr>
<tr>
<td>gateway</td>
<td>IP address</td>
<td>Set gateway address. Default is 172.31.&lt;slot_id * 3 + cpu_id + 1&gt;.254.</td>
</tr>
<tr>
<td>host-ip</td>
<td>IP address</td>
<td>Set host IP address. Default is 172.31.&lt;slot_id * 3 + cpu_id + 1&gt;.254.</td>
</tr>
<tr>
<td>host-mask</td>
<td># of bits</td>
<td>Set host mask length in bits. Default is 24 bits.</td>
</tr>
<tr>
<td>cpu-max-freq-non-turbo</td>
<td># of 100 MHz</td>
<td>Set CPU maximum frequency. Default is 0 (turbo enabled).</td>
</tr>
</tbody>
</table>

*continued...*
### Parameter Name | Available Values | Description
--- | --- | ---
bridge-interface | Name of the bridge network interface on the host or none to disable bridging | To enable bridging to the node, use the name of an existent bridge interface (for example, vcabr0). To disable bridging to the node, use none. Disabling is allowed if DHCP is disabled (meaning that the IP address already has a static value). The command is available since Intel® VCA Software Release 1.2.
node-name | Name of the node | Provide a unique name for each node in the system.
nfs-server | IP address or FQDN of NFS host for persistent image boot | Provide a path for the node to access persistent boot filesystem over the network. If using FQDN, name resolution must be operational
nfs-path | Path on NFS server where persistent filesystem is stored | Path to share on the NFS server. Use %s to indicate "node-name" value in the path.
block-devs | N/A | This is a section which describes some additional information about each defined VCA block device. By default there is only one entry: vcablk0. Another devices will appear if you add them using 'vcactl blockio open' command.
vcablk<N> | N/A | It is a root entry for each defined block device (where 0 ≤ N < 8).
mode | RW – read/write, RO – read-only, ramdisk – device will be created into RAM | This is a way (RW or RO) how VCA block device will be created. User can choose if block device may be read-only or with read/write permissions.
path | Path to block device. | Path to file used as VCA BlockIO device.
ramdisk-size-mb | Size of block device created inside node RAM. | VCA BlockIO device can be also created in node RAM memory (for example as SWAP partition as RAM is very fast memory type).
enabled | 1 – enable, 0 – disable | Option used to enable/disable block device. All enabled devices will be created/opened during booting node phase.
va-min-free-memory-enabled-node | 1 – enable, 0 – disable | Enable/disable minimum value (512 MB) of non-cached memory by Linux OS filesystem. This ensures that there will be enough free space to allocate buffers needed by virtual network over PCIe*. Option refers to node system (Linux only).

**A.3.20 vcactl config-use**

**A.3.20.1 Usage**

vcactl config-use

**A.3.20.2 Description**

Triggers the vcactld daemon to use the last configuration.

**A.3.21 vcactl config-show**

**A.3.21.1 Usage**

vcactl config-show [〈card_id〉 [〈cpu_id〉]] 〈parameter-name〉 〈parameter-value〉
A.3.21.2 Description

Shows the current configuration of the vcactld daemon.

```
[root@vcademo ~]# vcactl config-show 0 0
Global configuration:
  auto-boot: 1
  debug-enabled: 0
  link-up-timeout-ms: 2000
  handshake-irq-timeout-ms: 30000
  alloc-timeout-ms: 100
  cmd-timeout-ms: 1000
  mac-write-timeout-ms: 1000
  default-daemon-script:
  wait-cmd-timeout-s: 60
  wait-bios-cmd-timeout-s: 120
  wait-bios-cmd-flashing-s: 1200
  ICMP-ping-inverval-s: 1
  ICMP-response-timeout-s: 10
  card 0 cpu 0:
  os-image:
  last-os-image: /home/vista/vvgold/VCA_1.2.81/vca_baremetal_centos7.1_1.2.81.img
  script:
  daemon-script:
  ip: 172.31.1.1
  mask: 24
  gateway: 172.31.1.254
  host-ip: 172.31.1.254
  host-mask: 24
  cpu-max-freq-non-turbo: 0
  bridge-interface:
  node-name: vca_node_00
  nfs-server: 172.31.1.254
  nfs-path: /mnt/```

A.3.22 vcactl config-default

A.3.22.1 Usage

vcactl config-default

A.3.22.2 Description

Restores the vcactld daemon to default values.

A.3.23 vcactl info-hw

A.3.23.1 Usage

vcactl info-hw
A.3.23.2 **Description**

Displays hardware information for the Intel® VCAC-R card and its EEPROM version.

```shell
# vcactl info-hw
Card 0:VCAC-R, EEPROM version:VCAC-R 1.3 (CRC:4bb11a52), Serial Number:not-yet-readable
```

A.3.24 **vcactl info-system**

A.3.24.1 **Usage**

vcactl info-system

A.3.24.2 **Description**

Displays information of the software installed on the Intel® VCAC-R card including version and build date.

```shell
[root@localhost ] # vcactl info-system
Modules build: Build number: 2.6.265 build on: 2019-09-26 14:21:49 +0000
```

A.3.25 **vcactl pwrbtn-short**

A.3.25.1 **Usage**

vcactl pwrbtn-short [<card_id> [<cpu_id>]]

A.3.25.2 **Description**

- Power button toggle of CPU <cpu_id>
- Shutdown active OS on the specified CPUs or turn CPU on when it’s off. Command imitates short press the power button.

A.3.25.3 **Result**

- Command completes when CPU is off or on depending on previous state. All CPUs finish in `power_off` state in case of shutting down or in `bios_up` or `bios_ready` state when CPUs were off.

A.3.26 **vcactl pwrbtn-long**

A.3.26.1 **Usage**

vcactl pwrbtn-long [<card_id> [<cpu_id>]]
A.3.26.2 Description
- Power button override five seconds on CPU <cpu_id> to cut off Intel® VCA power supply immediately; the OS can be damaged. For comparison, vcactl pwrbtn-short first shuts down the OS gracefully, then cuts off Intel® VCA power supply.
- Normally, vcactl pwrbtn-short should be used to power off Intel® VCA. The vcactl pwrbtn-long command is only used when Intel® VCA is in strange mode and vcactl pwrbtn-short cannot power off the Intel® VCA card.
- CPU <cpu_id> is in power_off status until next vcactl pwrbtn-short.

A.3.26.3 Result
- Command completes when all CPUs finish in power_off state.

A.3.27 vcactl os-shutdown

A.3.27.1 Usage
vcactl os-shutdown [<card_id> [<cpu_id>]]

A.3.27.2 Description
Shuts down the running operating system on the specified CPU.

It is not recommended to use the os-shutdown command in combination with pwrbtn-short. (After using os-shutdown, it is necessary to wait some time before executing the pwrbtn-short command again to bring up CPU power.)

A.3.28 vcactl get-BIOS-cfg

A.3.28.1 Usage
vcactl get-BIOS-cfg [<card_id> [<cpu_id>]] [bios_cfg_name]

A.3.28.2 Description
Read BIOS configuration of the specified CPU. Available configurations to be read are:
- sgx
- gpu-aperture
- tdp.

A.3.28.3 Example
vcactl get-BIOS-cfg 0 1 sgx
A.3.29  vcactl set-BIOS-cfg

A.3.29.1  Usage

vcactl set-BIOS-cfg [<card_id> [cpu_id]] <bios_cfg_name> <bios_cfg_value>

A.3.29.2  Description

Set/change BIOS configuration of specified CPU. Available configurations to be read are:

- **sgx**: Enable/disable Intel® Software Guard Extensions. Set to *enable* or *disable*.
- **gpu-aperture**: Megabytes of graphics memory. Set to 128, 256, 512, 1024, 2048, or 4096.
- **tdp**: Set to 0 to 11, where zero means base value, 1 means base value + 1, etc.

A.3.29.3  Examples

vcactl set-BIOS-cfg 1 0 sgx enable
vcactl set-BIOS-cfg gpu-aperture 1024

A.3.30  vcactl info

A.3.30.1  Usage

vcactl info <subcmd> [<card_id> [cpu_id]]

A.3.30.2  Description

Command allows to read specific information about either Intel® VCA SW/FW or Node OS. The subcommands are the following and work on all or on the specified node:

- **BIOS**: Displays BIOS version of the Intel® VCA2 nodes.
- **hw**: Displays hardware information for the Intel® VCA card including if the card is GEN 1 or GEN 2 and its EEPROM version.
- **system**: Displays information of the software installed on the Intel® VCA card including version and build date.
- **node-os**: Displays information of node OS on the Intel® VCA card.

A.3.30.3  Examples

vcactl info hw
vcactl info BIOS
Appendix B Setting up Radeon™ GPU for Gaming

When Intel GPU is used as the default, the Radeon™ GPU has to be explicitly set for the game to achieve adequate performance.

Adding the profile for the game
1. Install the game and see if it works. Use Task Manager to locate the executable of the game.
2. Right-click on the desktop, and choose "Radeon RX Vega M Settings" as shown below:

3. In the window that opens, choose System tab
4. Then, switch to Switchable Graphics view and click on Running Applications caption to reveal a dropdown list. Choose Installed Profiled Applications as shown in the figure below:

5. Click the Browse button and locate the game executable.

6. A box for the game should appear. Make sure that it has High Performance enabled. If not, click the arrow and choose appropriate setting for the game executable.
After these steps, the game should run on the fast Radeon graphics card. However, some extra steps may be required during each restart – they are described in next section.

**Restoring the setting after restart**

After resetting the node, the effect of setting the Radeon GPU to handle the game may be lost. To recover it, the following steps have to be done after each reset:

1. Repeat steps 2 to 4 of the list in above mentioned section **Adding the profile for the game**.

2. On any of the boxes corresponding to game executables (from the dropdown list), choose **High Performance** as in figure in step 6 above.

**NOTE**

This needs to be done even if the box already says **High Performance**.

Now all the games configured as in previous section should operate on Radeon GPU until next reset.
## Glossary

<table>
<thead>
<tr>
<th>Abbreviation</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>acgss</td>
<td>Android Cloud Gaming Software Stack</td>
</tr>
<tr>
<td>AIC</td>
<td>Android in Container</td>
</tr>
<tr>
<td>NAT</td>
<td>Network Address Translation</td>
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<td>VCA</td>
<td>Visual Compute Accelerator</td>
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<tr>
<td>VCAC-R</td>
<td>Visual Cloud Accelerator Card - Rendering</td>
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